

Smooth Evolution Path from Legacy to NGN Synchronization

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Outline

- Drivers of the evolution
- Dimensions of the evolution
- Evolution starting points
- Evolution phases and end points
- Evolution path examples
- Conclusions



Driver of the evolution

 Network technology evolution from TDM to packet-switched networks, and from fixed to fixed & mobile end sytems



Synchronization in the past:

• Driver: TDM switching (telephony) and transmission (SDH)

Reasons: limit under- and overflowing of frame buffers,

allow crossconnecting (SDH)

• Requirements: frequency, accuracy 1·10⁻¹¹ (relative freq. acc.)



Synchronization at present and in the future:

• Driver: mobile base stations, e.g. 2G BTS, 3G Node B, 4G eNB

Reasons: successful call handover

efficient use of sparse spectrum & channel capacity

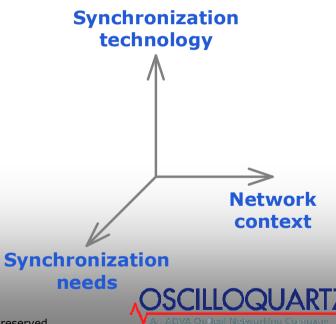
etc.

• Requirements: frequency (1.6E-8) and phase (1.5 μ s \rightarrow hundreds ns)



Dimensions of the evolution

- Change in synchronization needs
 - Old: frequency for the entire network (1E-11)
 - New: frequency (1.6E-8) and phase (1.5 $\mu s \rightarrow$ hundreds ns) for the network edge
- Change in network technology
 - Old: TDM networks (PDH, SDH)
 - New: packet-switched networks
 - Ethernet, Synchronous Ethernet (SyncE)
 - IP, IP/MPLS
 - Etc.
- Change in synchronization technology
 - Old: SDH/SONET, E1/T1 over PDH
 - New: SyncE, PTP (IEEE 1588 v2)

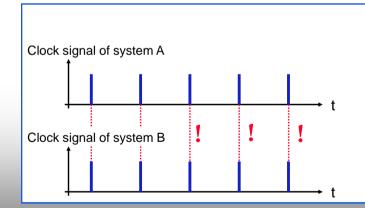


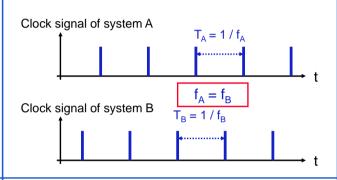
Once more: frequency, phase and time-of-day

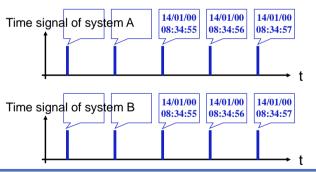


System B

- Frequency synchronization
- Phase synchronization
- Time-of-Day synchronization







Frequency and phase synch. requirements

Application	Radio Interface		Backhaul	
	Frequency	Phase	Frequency	Phase
CDMA 2000	±50ppb	±3 to 10μs	GPS	GPS
GSM	±50ppb	n/a	±16ppb	n/a
WCDMA	±50ppb	n/a	±16ppb	n/a
LTE (FDD)	±50ppb	n/a	±16ppb	n/a
LTE (TDD)	±50ppb	±1.5µs	±16ppb	±1.1μs
LTE-A MBMS	±50ppb	±1 to 5µs	±16ppb	±1µs (G.8271)
LTE-A CoMP LTE-A CoMP JT	±50ppb	±1 to 5μs ± 0.5μs	±16ppb	±1.1µs < 0.5µs (?)
LTE-A eICIC	±50ppb	±1 to 3µs	±16ppb	±1.1µs

CoMP: Coordinated

MBMS: Multimedia Broadcast Multicast Services

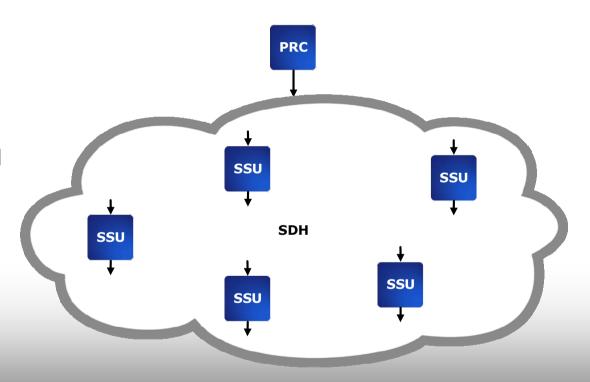
ultipoint

eICIC: enhanced Inter-Cell Interference Coordination JT: Joint Transmission © 2014 ADVA Optical Networking. All rights reserved.



Starting point 1: central PRC

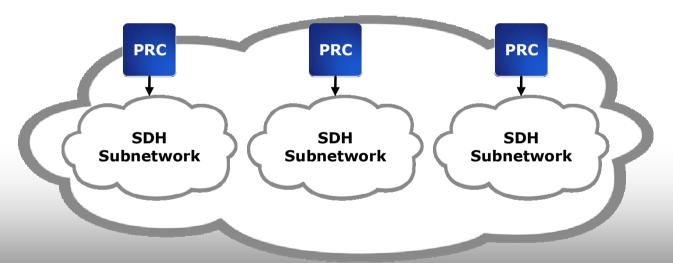
- Frequency synchronization with accuracy = 1E-11
- Generation: central PRC, typically atomic Cesium clock
- Distribution: SDH, physical layer; sometimes E1/T1 in «last mile»





Starting point 2: distributed PRCs

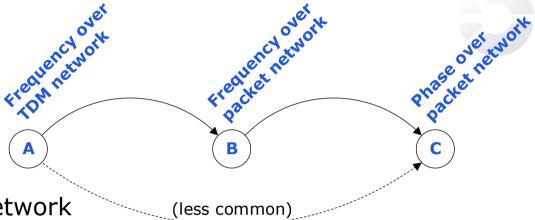
- Frequency synchronization with accuracy = 1E-11
- Generation: distributed PRCs, typically GNSS receivers
- Distribution: SDH, physical layer; sometimes E1/T1 in «last mile»





Transition phases

Main transition phases:



- A: Frequency over TDM network
 - SDH/SONET
- B: Frequency over packet network
 - SyncE
 - PTP / No Timing Support (G.8265.1)
- C: Phase over packet network
 - PTP / Full Timing Support (G.8275.1) with SyncE
 - PTP / Full Timing Support (G.8275.1) without SyncE (ITU-T: «ffs»)
 - PTP / Assisted Partial Timing Support (G.8275.2)



Many evolution scenarios



B / A	SDH & PDH	
SyncE	X	
G.8265.1	x	

Transition $B \rightarrow C$

C / B	SyncE	G.8265.1	
G.8275.1	X	X	
G.8275.2	X	X	

Transitions $A \rightarrow B \rightarrow C$:

SDH & PDH	\rightarrow	SyncE	\rightarrow	G.8275.1
SDH & PDH	\rightarrow	SyncE	\rightarrow	G.8275.2
SDH & PDH	\rightarrow	G.8265.1	\rightarrow	G.8275.1
SDH & PDH	\rightarrow	G.8265.1	\rightarrow	G.8275.2

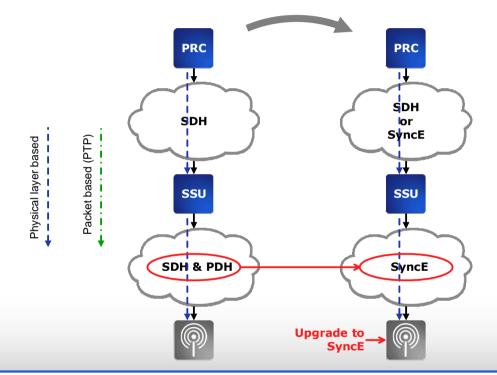


There are more evolution scenarios than that!

- Already mentioned: Starting point (SDH & PDH) can be with centralized or with decentralized PRCs
- There are multiple mobile systems (2G, 3G, 4G); evolution scenarios may be different for each of them
- Multiple network ownerships (mobile operator, transport provider, etc.)
- Networks with equiment from multiple vendors: different equipment roadmaps
- Some operators use CES/PWE for their 2G BTS (PDH over packet network)
- And we haven't mentioned WDM systems in conjunction with phase synchronization ...
- Etc., etc.



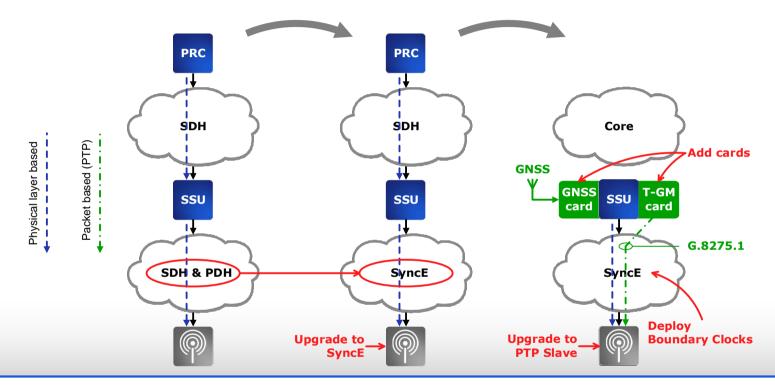
Evolution example 1a: SDH & PDH → SyncE → G.8275.1



Leverage existing PRC and SSUs



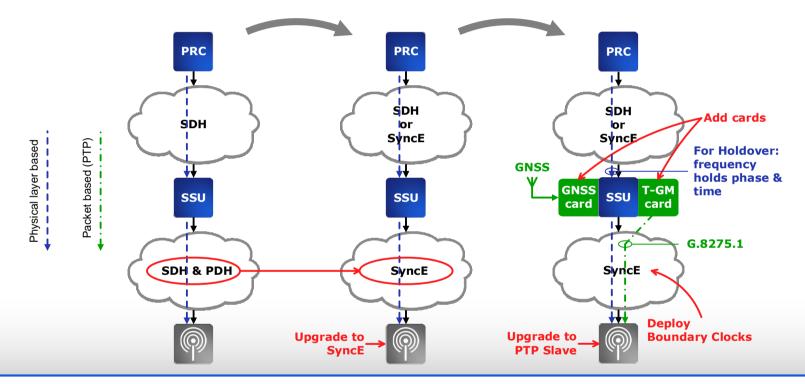
Evolution example 1a: SDH & PDH → SyncE → G.8275.1



Leverage existing PRC and SSUs, just add cards to SSUs for phase



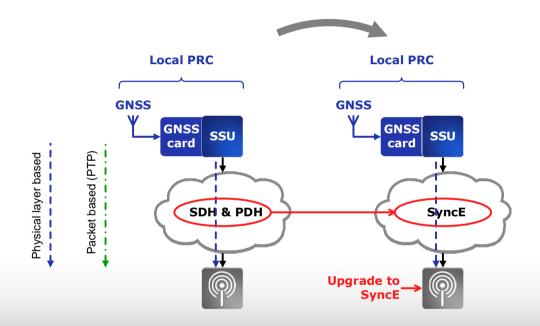
Evolution example 1b: keep PRC for phase holdover



Leverage existing PRC and SSUs, just add cards to SSUs for phase



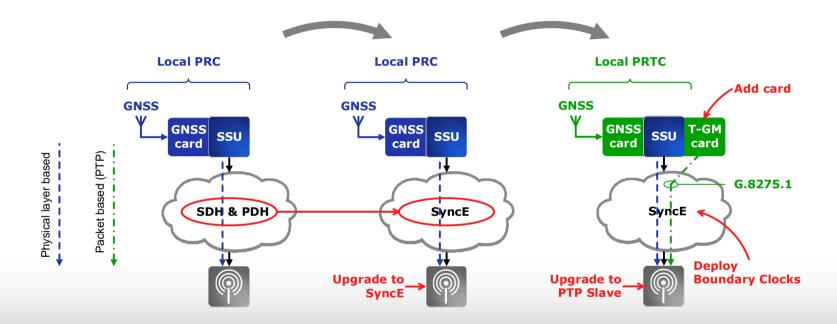
Evolution example 1c: starting with decentralized PRCs



Leverage existing GNSS/SSUs, just add T-GM card to SSUs for phase



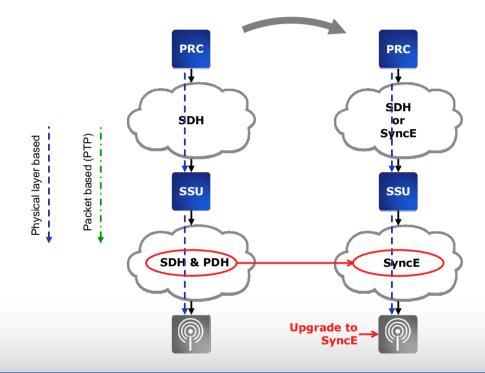
Evolution example 1c: starting with decentralized PRCs



Leverage existing GNSS/SSUs, just add T-GM card to SSUs for phase



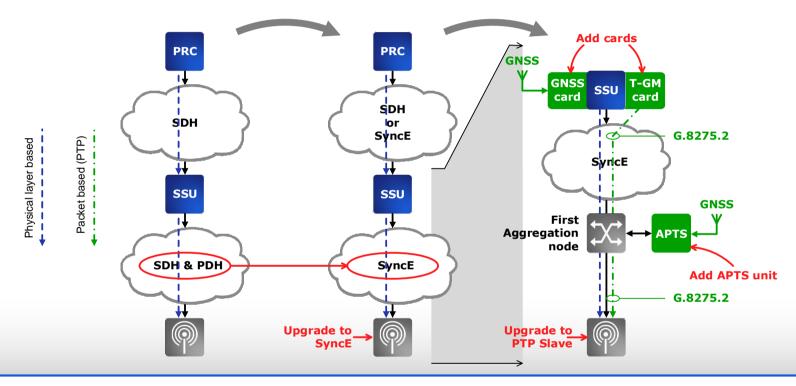
Evolution example 2a: sdh & PDH -> SyncE -> G.8275.2



Add cards to SSUs and add small APTS units for phase



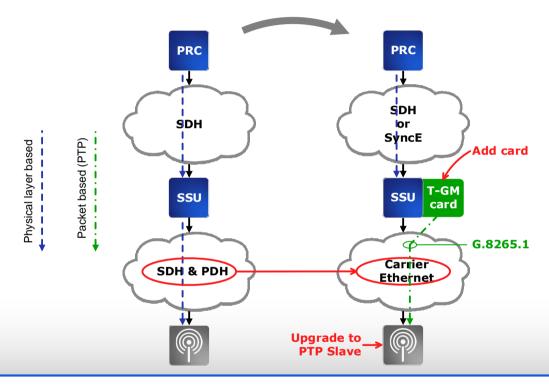
Evolution example 2a: SDH & PDH -> SyncE -> G.8275.2



Add cards to SSUs and add small APTS units for phase



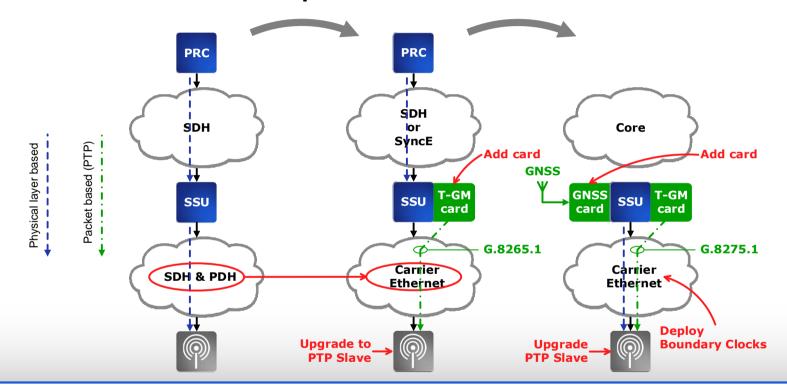
Evolution example 3a: $SDH \& PDH \rightarrow G.8265.1 \rightarrow G.8275.1$



Leverage existing PRC and SSUs, just add cards to SSUs for phase



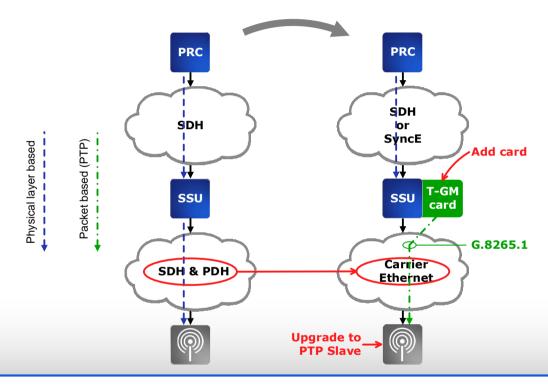
Evolution example 3a: $SDH \& PDH \rightarrow G.8265.1 \rightarrow G.8275.1$



Leverage existing PRC and SSUs, just add cards to SSUs for phase



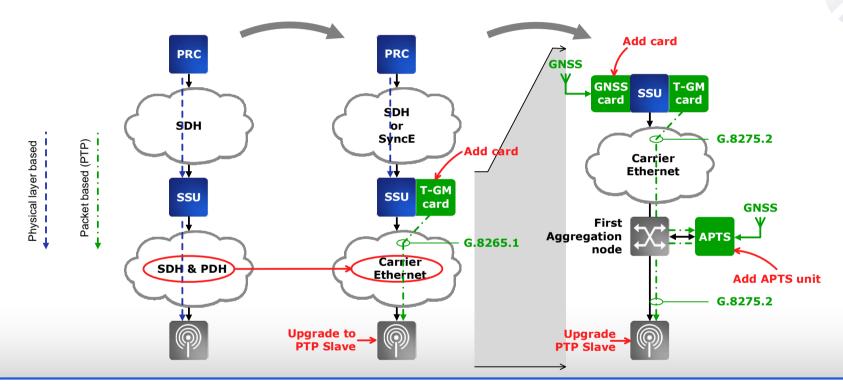
Evolution example 4a: sdh & pdh → G.8265.1 → G.8275.2



Add cards to SSUs and add small APTS units for phase



Evolution example 4a: $SDH & PDH \rightarrow G.8265.1 \rightarrow G.8275.2$



Add cards to SSUs and add small APTS units for phase



Conclusions

- Evolution is driven by changes in synchronization needs, network context and synchronization technologies
- There are many possible evolution scenarios
- Leveraging existing SSUs and PRCs is possible with many evolution scenarios
- Within these scenarios, evolution requires addition on T-GM cards in SSUs, and possibly addition of small APTS units
- Chosen evolution path has important impact on CAPEX
- Optimal planning of the evolution path is a must





Thank you

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