

The Fundamental Need for Synchronization

ITSF 2014, Budapest

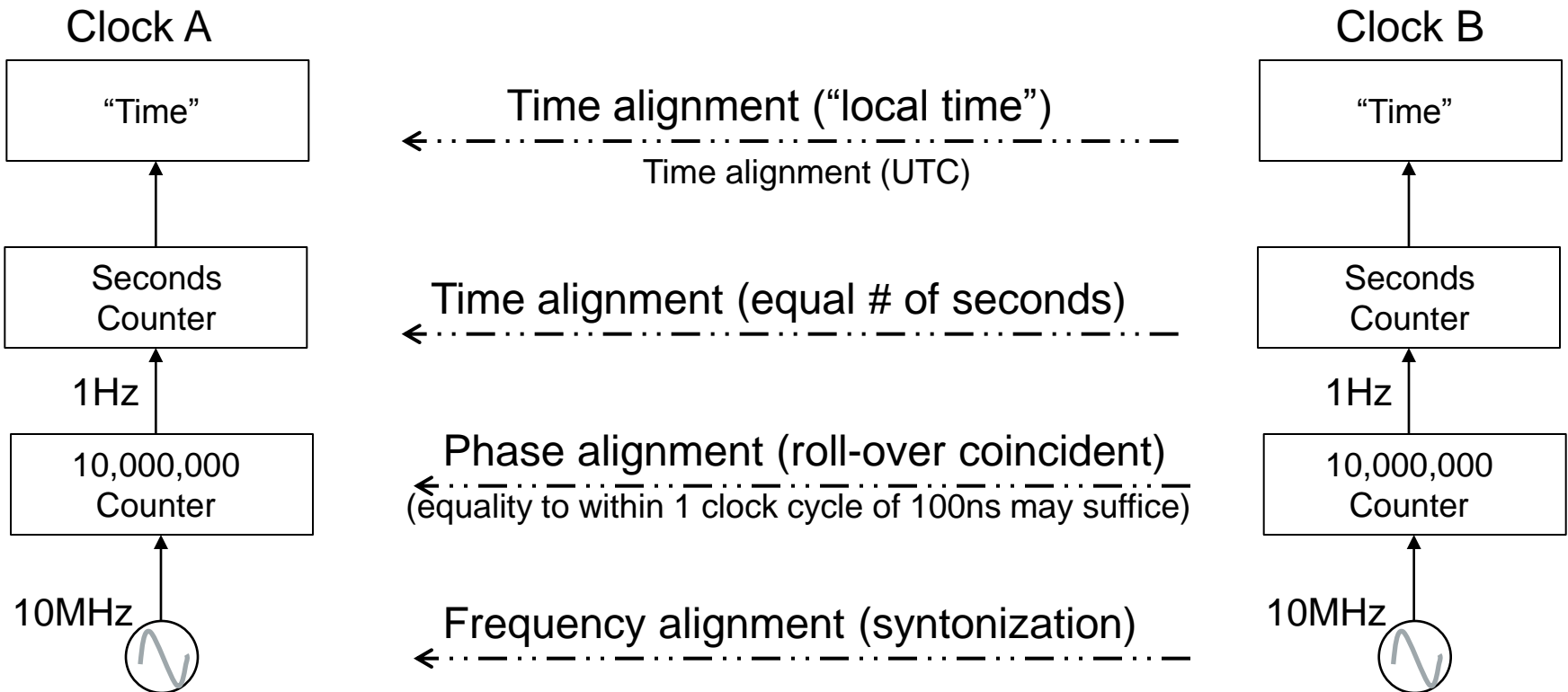
Time to Learn – Tutorial Session

Kishan Shenoi (kshenoi@Qulsar.com)

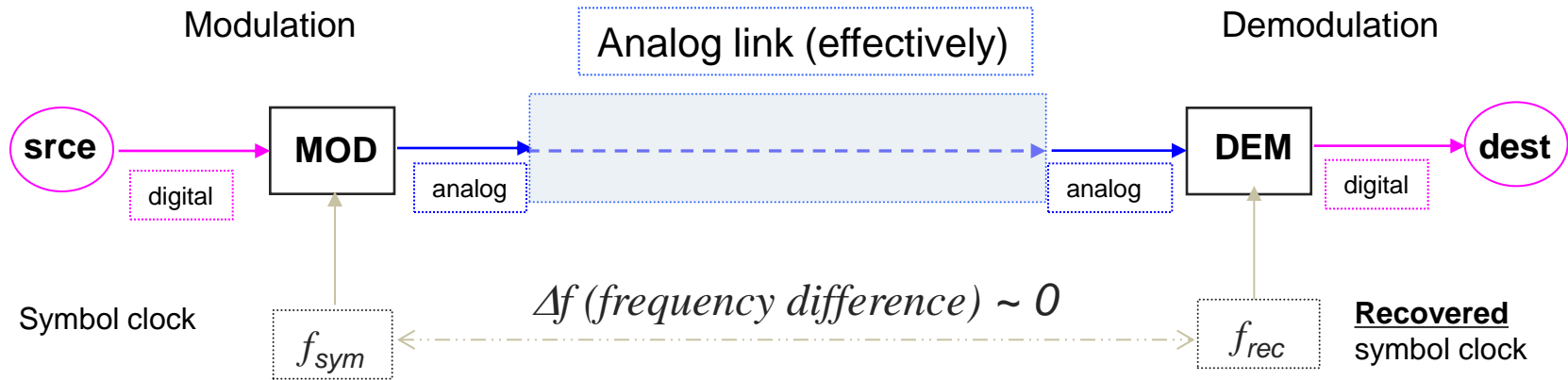
Qulsar, Inc., San Jose, California

- ▶ Notion of Timing Alignment
- ▶ Timing Alignment is Fundamental in Telecommunications
 - ▶ Digital transmission requires symbol-timing alignment
 - ▶ Digital network require synchronization to emulate analog channels
 - ▶ Circuit Emulation (CBR over packet) requires timing alignment
 - ▶ Wireless (Cellular) requires timing alignment
 - ▶ Multimedia requires timing alignment
- ▶ Timing in Circuit-Switched (TDM) Networks
 - ▶ Synchronous time-division multiplexing
- ▶ Timing in Next Generation Networks
 - ▶ Impact of packet delay variation (PDV)
 - ▶ Principle of timing over packet networks
 - ▶ Introduction to packet (PDV) metrics

- ▶ Aligning two time clocks (synchronization) implies:
 - ▶ Make frequency B = frequency A (syntonization)
 - ▶ Make phase B = phase A (e.g. roll-over instant of 10^7 counter)
 - ▶ Make seconds B = seconds A (elapsed time equal; same time origin)
 - ▶ Choose same formatting convention (and time-zone, etc.)

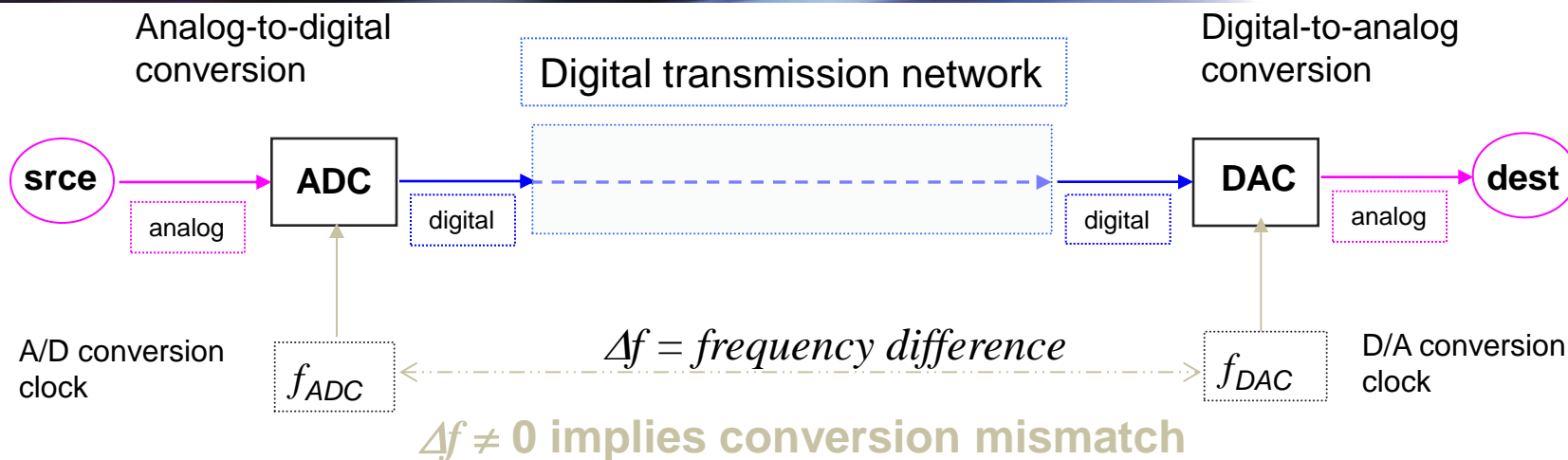


Data transmission schemes require synchronization



- ▶ Source/Destination : modulator and demodulator
- ▶ Transmitter (modulator) uses a particular symbol clock
 - ▶ receiver (demodulator) must extract this clock ($\Delta f \sim 0$) for proper data recovery
- ▶ The “Analog link” must, *effectively*, mimic an analog wire pair
 - ▶ Frequency translation (e.g. DSB-AM) is benign, Doppler (pitch modification effect, PME) is not benign ($\Delta f \sim$ Doppler)

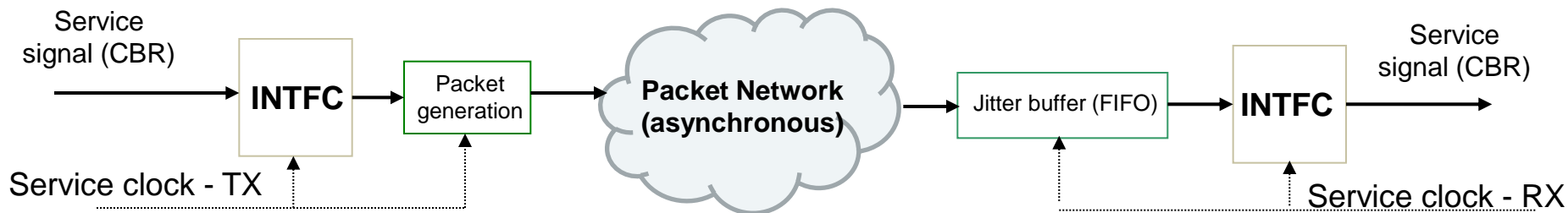
Timing Alignment required in Voice-Band Transmission



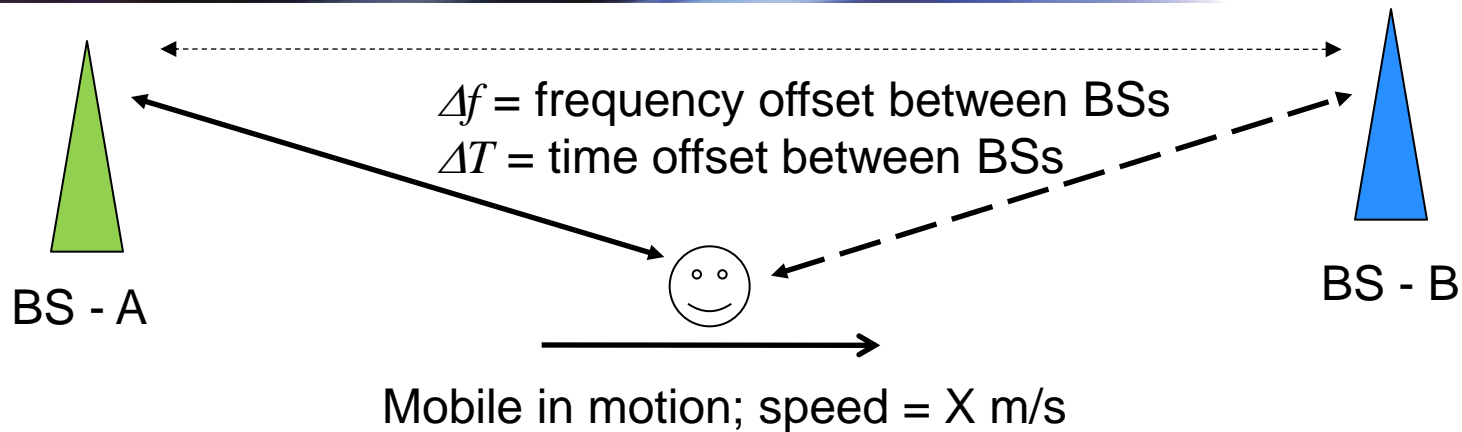
Primarily affects voice-band data (Fax, modem) and real-time video

- ▶ Source/Destination : Voice/video/fax terminal
- ▶ The digital transmission network *emulates* an analog circuit (the original circuit emulation)
- ▶ Impact of frequency difference (Δf):
 - ▶ Eventually buffers will overflow/underflow (e.g. slips) (“obvious”)
 - ▶ Pitch Modification Effect (PME) (analogous to *Doppler*) makes recovered symbol clock \neq transmit symbol clock (not so “obvious”)
 - ▶ Recovered waveform \neq original waveform (more than just additive noise)

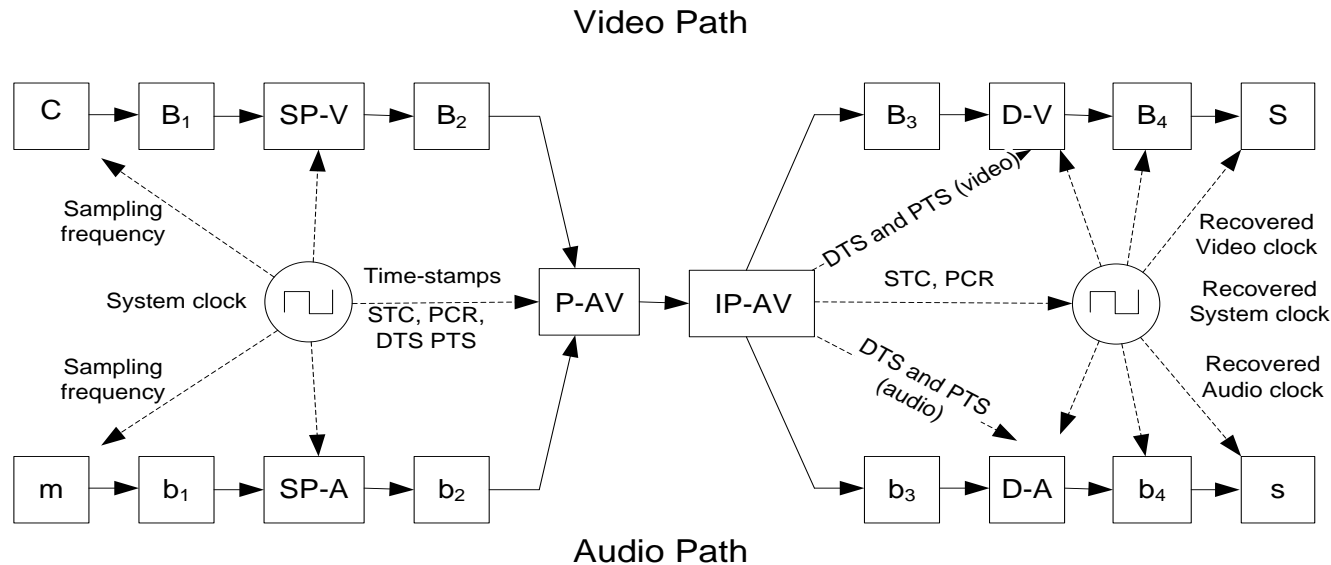
Timing alignment implicit in Circuit Emulation



- Network impairments: delay, packet-delay-variation (PDV), discarded packets
- Jitter buffer size: large enough to accommodate greatest (expected) packet-delay-variation. Packet loss concealment is not an option.
- Causes of packet “loss”:
 - Network drops packets (bit errors, congestion)
 - Jitter buffer empty/full (excessive packet-delay-variation)
- Key to **Circuit Emulation** :
 - Ensure packet loss is (essentially) zero.
 - **Make RX and TX service clocks “equal”.**
 - **Note: If $RX \neq TX$ then jitter buffer is going to overflow/underflow**



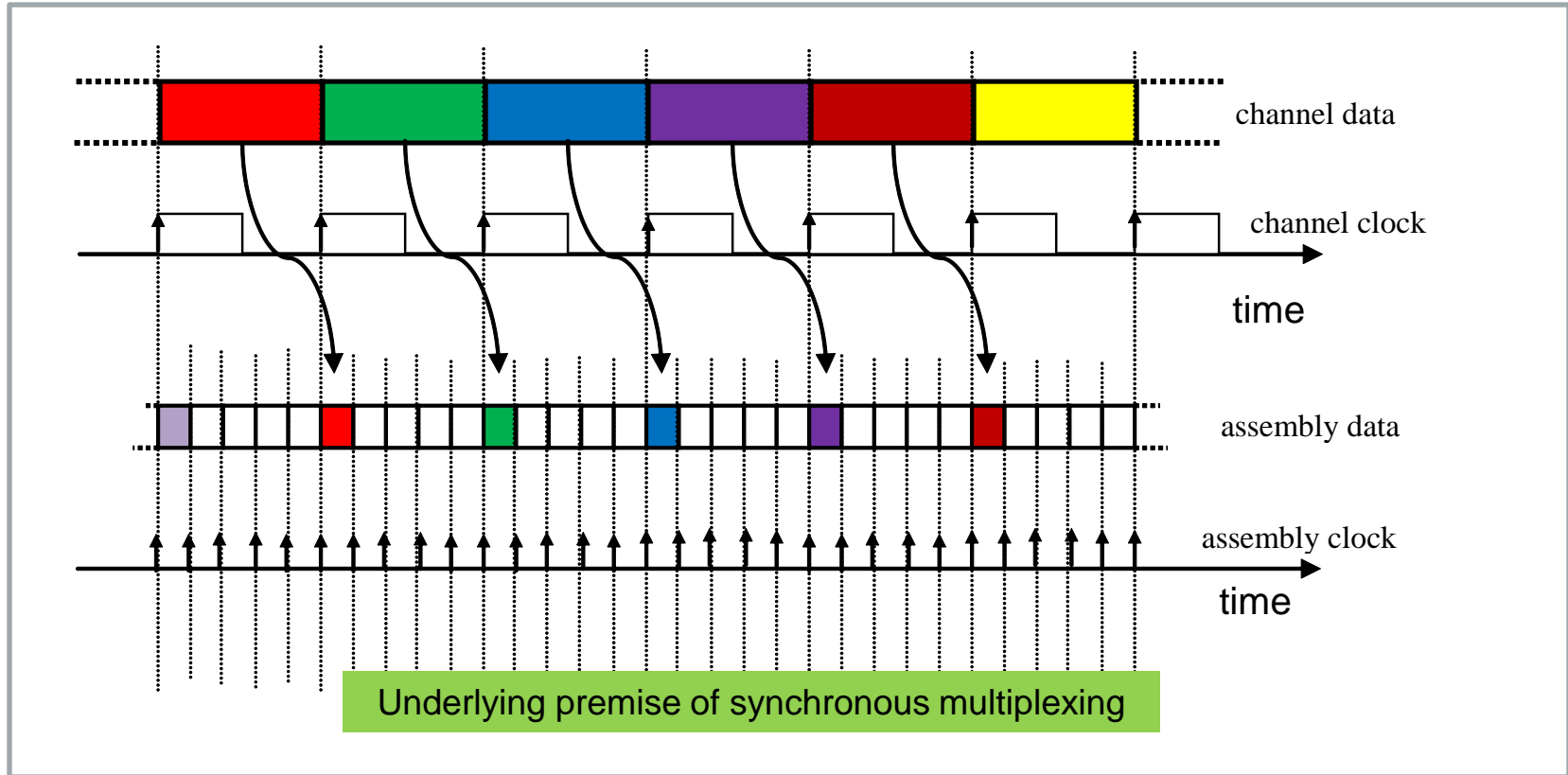
- ▶ When hand-over occurs, the mobile must reacquire carrier frequency
 - ▶ Mobile in motion (X m/s) introduces a Doppler shift (X/c)
 - ▶ Loop bandwidth wide enough to handle ($\Delta f + X/c + LO$) (LO = local oscillator offset)
 - ▶ Loop bandwidth should be small from a noise rejection viewpoint
 - ▶ Large Δf compromises the reliability of hand-over
- ▶ TDD networks require time/phase alignment between A & B
- ▶ LTE-TDD & LTE-Advanced require ΔT to be small (microsec) for providing the more bandwidth intensive features



- ▶ Frequency offset (wander) between audio and video sampling results in loss of lip-sync
- ▶ Frequency offset (wander) between send-side and receive-side system clock results in freeze (video), breaks (audio), and possible loss of lip-sync
- ▶ Audio and video streams could come from diverse sources requiring the sources to be synchronized to a common (global) reference

- ▶ Synchronization is essential for synchronous multiplexing
 - ▶ To avoid information loss
- ▶ Synchronous multiplexing assemblies are used as carriers of timing information (DS1/E1, SONET/SDH)
 - ▶ The recovered line clock is used as a reference for the BITS
 - ▶ The transmit signals must meet the “sync” mask for timing information
- ▶ Asynchronous multiplexing can preserve timing (up to a point) *if done correctly*
- ▶ Bearer signals (DS1/E1) in asynchronously multiplexed assemblies (e.g. DS1 in DS3) can be used as carriers of timing
 - ▶ Asynchronous multiplexing is done correctly
- ▶ DS1/E1 bearer signals in SONET/SDH are not suitable as carriers of (good) timing
 - ▶ SONET/SDH encapsulation of DS1/E1 was done in a way that protects data but not (good) timing information

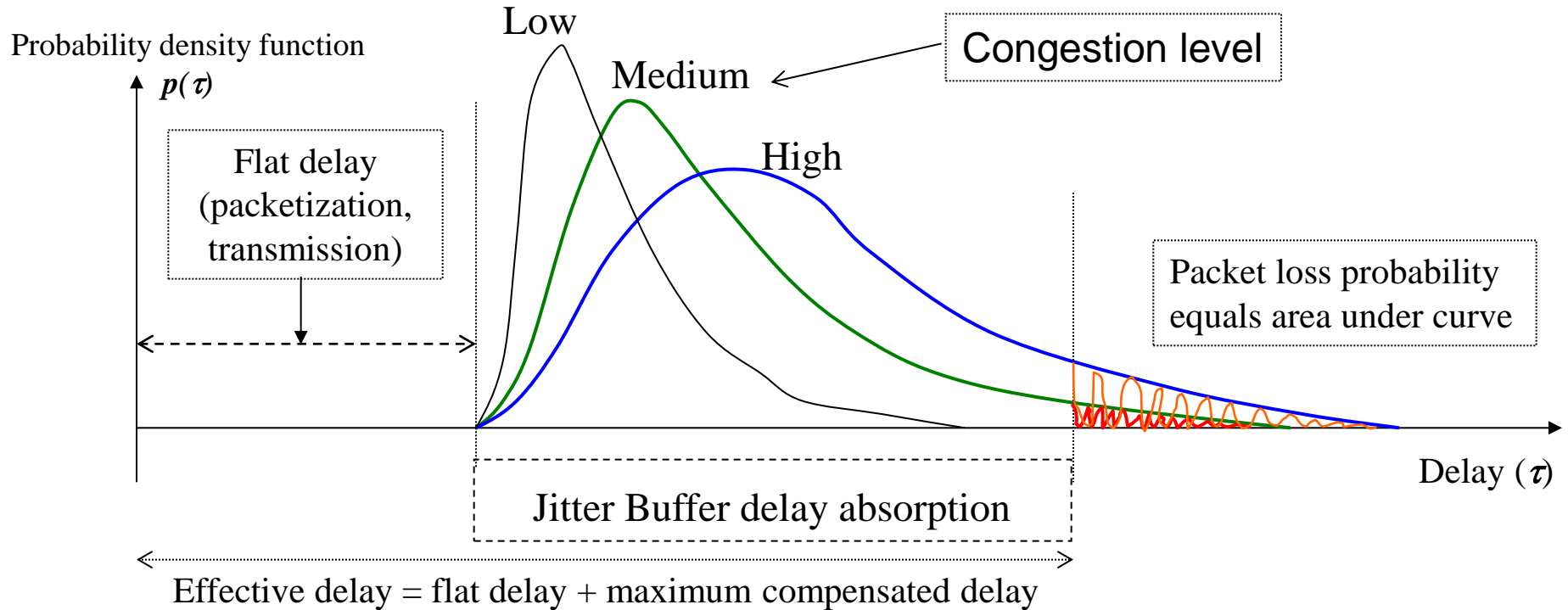
Synchronous Multiplexing



- Predetermined (rigid) ratio between channel clock and assembly clock
- 1-to-1 correspondence between channel bits and allowed bit positions
- *Fractional frequency difference between channel and assembly clocks = 0*

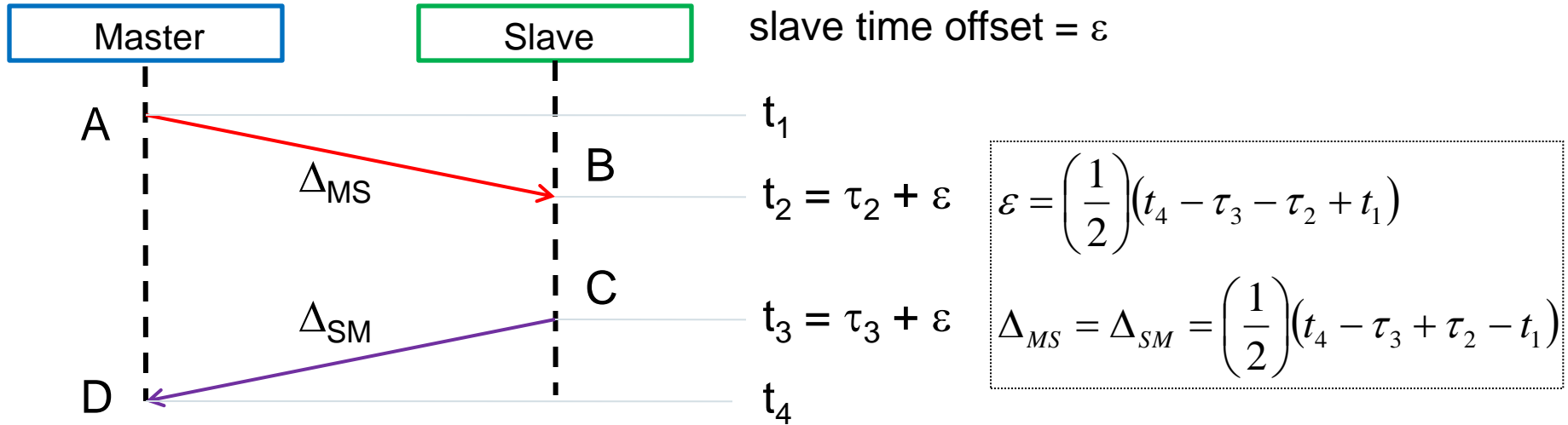
- ▶ Next generation networks are based on packet switching as opposed to circuit-switched (i.e. based on TDM)
 - ▶ Significant impact of variable delay (packet delay variation)
- ▶ Timing requirements remain.
 - ▶ Going “IP” does not mean that real-time services no longer need synchronization!
- ▶ Transition Phase:
 - ▶ Hybrid Networks (IP/TDM islands)
 - ▶ Circuit Emulation
- ▶ Timing over Packet Networks (packet-based methods)
 - ▶ PTP, NTP, adaptive clock recovery
- ▶ Monitoring and Testing
 - ▶ Metrics for packet-based timing methods (quantifying PDV)

Impact of Packet Delay Variation – VoIP example



- Jitter buffer size: trade-off between latency and packet loss
 - Minimize latency (delay) for voice calls
 - Minimize packet loss for data (voice-band modem) calls
- “Adaptive” jitter buffer techniques adjust buffer size to match PDV
 - Introduce delay for “faster” packets
 - **Frequency offset (wander) is a problem**

Principles of Packet-based timing methods



- One exchange of packets (M-to-S and S-to-M) provides 4 time-stamps
 - Master knows t_1 and t_4 ; Slave knows τ_2 and τ_3
- t_x is correct time (master) ; τ_x is the slave's idea of time (offset of ε)
- Assumption: transit time from master-to-slave (Δ_{MS}) is equal to the transit time from slave-to-master (Δ_{SM})
- “Errors” arise because the transit time is not the same from packet to packet (packet delay variation) and the path is not reciprocal ($\Delta_{SM} \neq \Delta_{MS}$)

- ▶ Metrics that quantify PDV and share light on the ability of slave clocks to properly recover timing (phase and/or frequency)
- ▶ General background principles:
 - ▶ Not every packet has “good” timing information. Excess PDV is best ignored (“packet selection”).
 - ▶ For a given path, the floor delay is not load dependent (“lucky packet”) though congestion may make it “unobservable”.
 - ▶ Metrics often characterize the “floor behavior”, quantifying:
 - ▶ Amplitude distribution (pdf) of the PDV to indicate the number of packets that are near the floor
 - ▶ the temporal/spectral characteristics of the PDV associated with these packets

- ▶ **Timing Alignment is Fundamental in Telecommunications**
 - ▶ Digital transmission requires symbol-timing alignment
 - ▶ Digital network require synchronization to emulate analog channels
 - ▶ Circuit Emulation (CBR over packet) requires timing alignment
 - ▶ Wireless (Cellular) requires timing alignment
 - ▶ Multimedia requires timing alignment
- ▶ **Timing in Circuit-Switched (TDM) Networks**
 - ▶ Synchronous time-division multiplexing is based on streams being aligned in frequency
- ▶ **Timing in Next Generation Networks**
 - ▶ Packet-based timing transfer can be achieved by using time-stamped packets
 - ▶ Packet delay variation (PDV) adversely affects user Quality of Experience and quality of timing alignment in packet-based clocks

Thank You!



Questions?

Kishan Shenoi (kshenoi@Qulsar.com)