

# TIME SYNC IN ITU-T Q13/15: G.8271 AND G.8271.1

ITSF - 2012, Nice

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# TIME SYNCHRONIZATION: SCOPE AND PLANS



- › The work recently started in ITU-T Q13/15
- › The following main aspects need to be addressed
  - Network Requirements
  - Architecture
  - PTP Profiles
  - Clocks
- › The work is tentatively planned to be completed in the 2013/2014 time frame
- › Several aspects also involving other Questions, e.g.:
  - Time sync Interfaces
  - Time sync over access technologies
  - Time sync over OTN

# TIME SYNC: Q13/15 RECOMMENDATIONS



- › Analysis of Time/phase synchronization in ITU-T Q13/15:
  - G.8260 (definitions related to timing over packet networks)
  - G.827x series

|                                     | Frequency | Phase/Time         |
|-------------------------------------|-----------|--------------------|
| <b>General/Network Requirements</b> | G.8261    | G.8271             |
|                                     | G.8261.1  | G.8271.1           |
| <b>Architecture and Methods</b>     | G.8264    | G.8275             |
|                                     | G.8265    |                    |
| <b>PTP Profile</b>                  | G.8265.1  | G.8275.1, G.8275.2 |
| <b>Clocks</b>                       | G.8262    | G.8272             |
|                                     | G.8263    | G.8273             |
|                                     |           | G.8273,.1,.2,.3    |

# G.8271: TIME AND PHASE SYNC ASPECTS OF PACKET NETWORKS



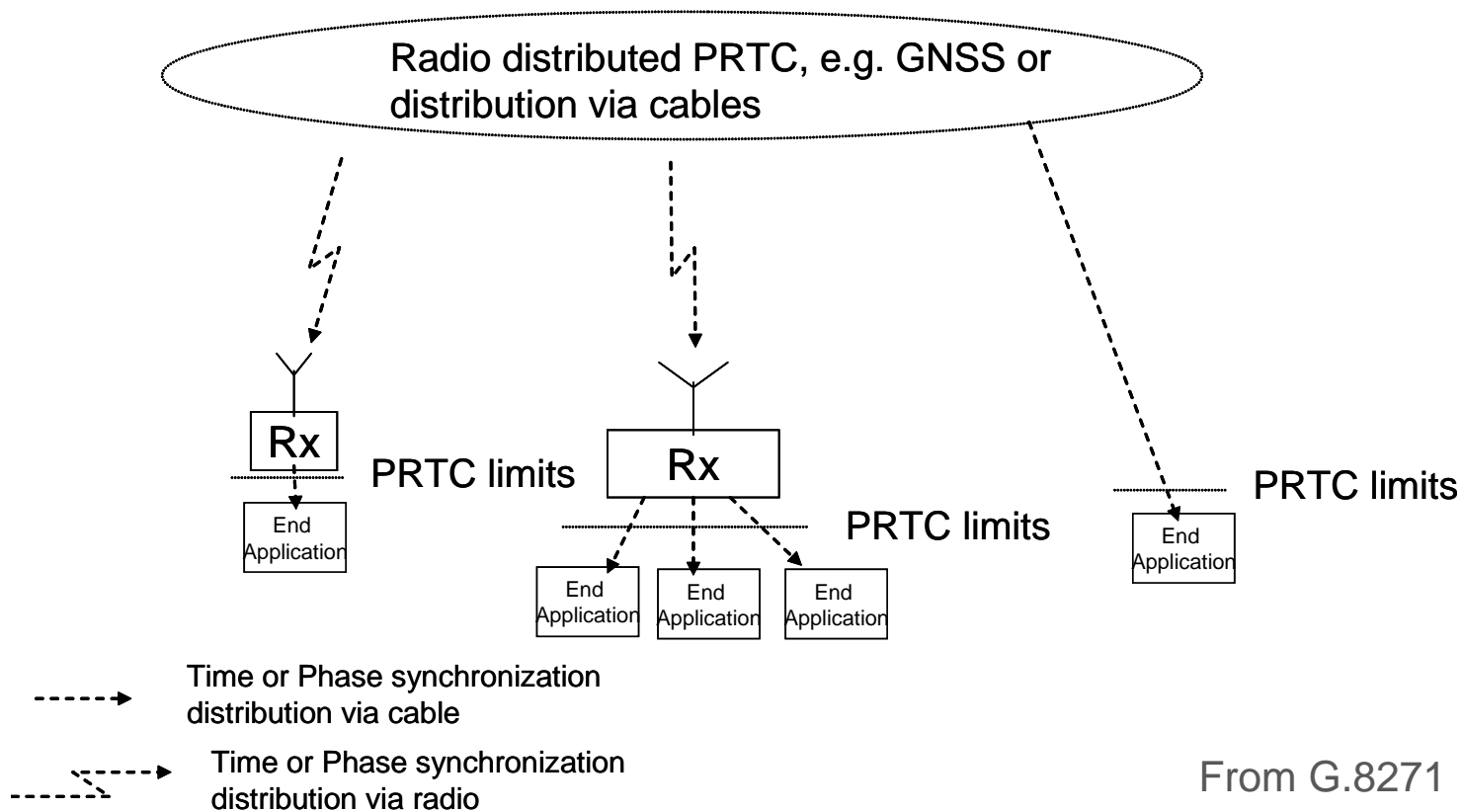
- › G.8271 scope
  - Time and phase synchronization aspects in packet networks
    - › Target applications
    - › Methods to distribute the reference timing signals
- › It also specifies the relevant time and phase synchronization interfaces and related performance.
  - *Physical characteristics to be moved into G.703*
- › G.8271 is the first document of the G.827x series to be released (Published in 02/2012)
  - Amendment planned for 2013 (additional details and alignments with G.8271.1)

# TARGET APPLICATIONS

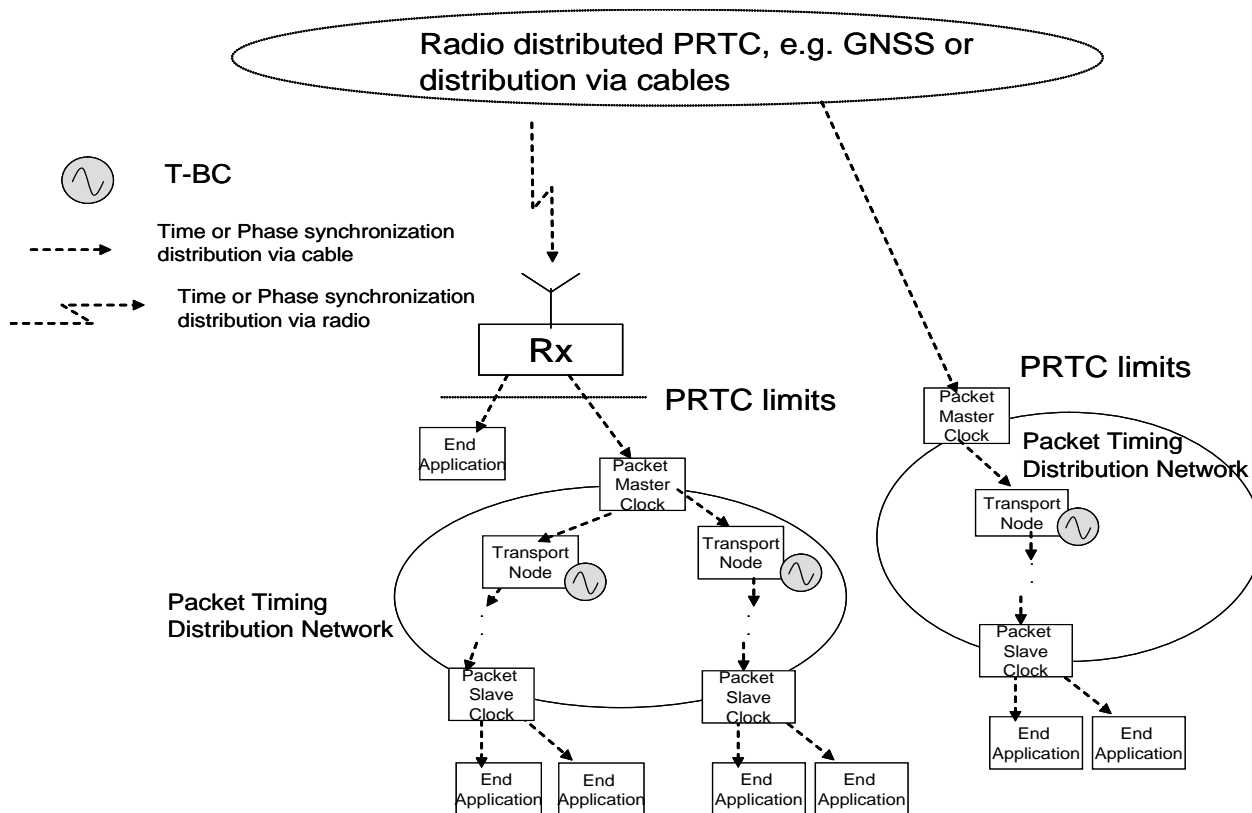


| Level of Accuracy | Range of requirements<br>(with respect to ideal reference) | Typical Applications                                    |
|-------------------|--|---|
| 1                 | 1 ms – 500 ms  | Billing, Alarms   |
| 2                 | 5 $\mu$ s – 100 $\mu$ s<br>(Note 1)                        | IP Delay monitoring                                     |
| 3                 | 1.5 $\mu$ s - 5 $\mu$ s                                    | LTE TDD (large cell)<br>Wimax-TDD (some configurations) |
| 4                 | 1 $\mu$ s - 1.5 $\mu$ s                                    | UTRA-TDD,<br>LTE-TDD (small cell)                       |
| 5                 | x ns - 1 $\mu$ s<br>(x ffs)                                | Wimax-TDD (some configurations)                         |
| 6                 | < x ns<br>(x ffs)  | Some LTE-A features<br>(Under Study)                    |

# METHODS: DISTRIBUTED PRTC



# METHODS: PACKET BASED METHODS



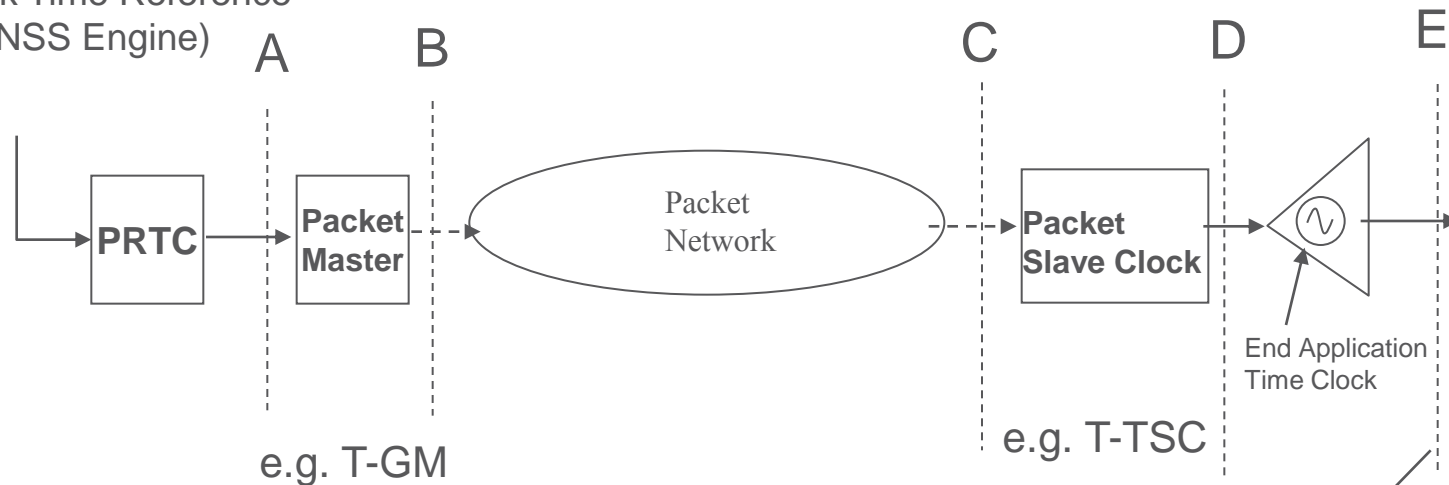
From G.8271

# NETWORK REFERENCE MODEL



N Common Time Reference (e.g. GPS time)

Network Time Reference  
(e.g. GNSS Engine)



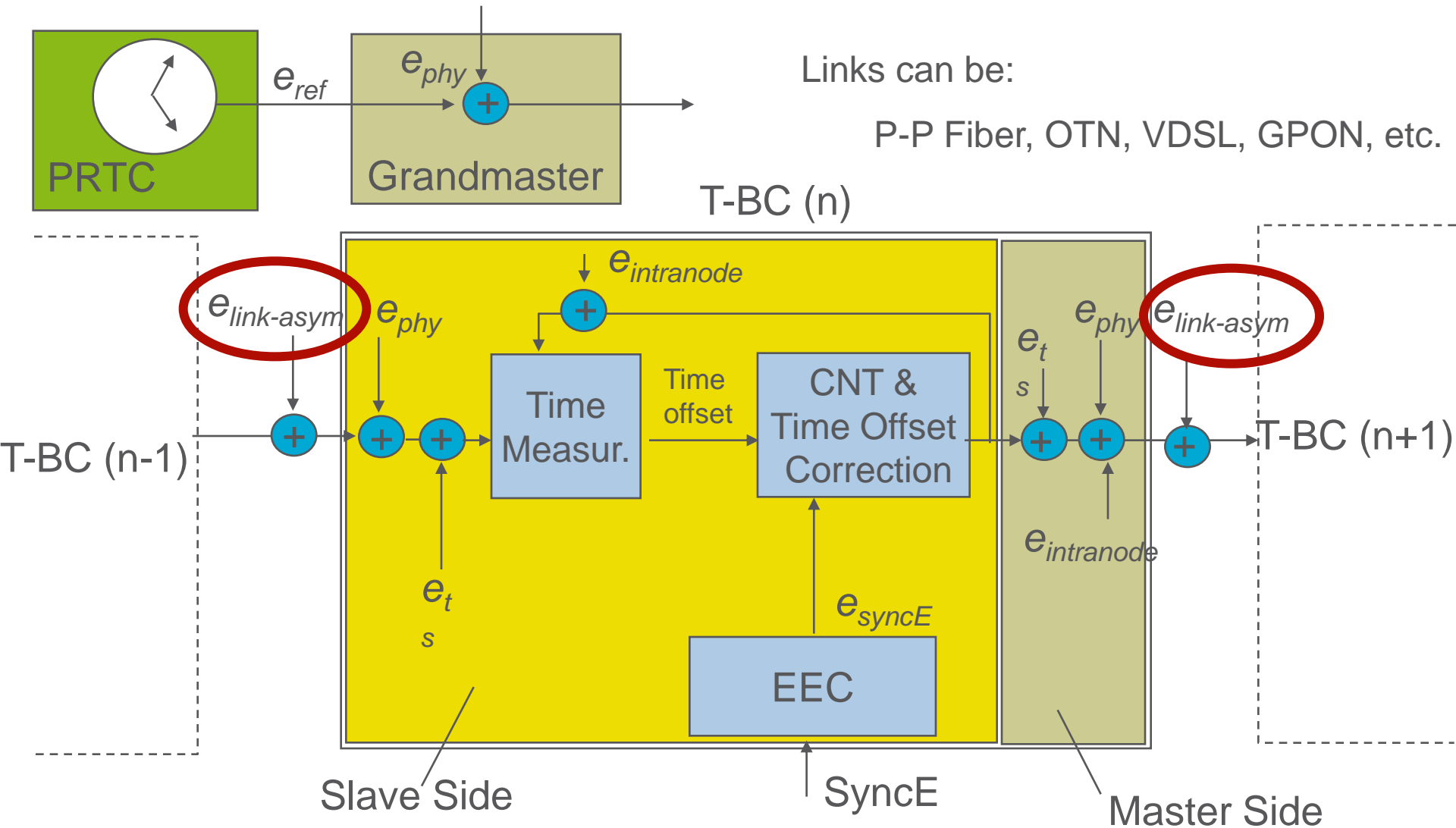
Typical Target Requirements  $TE_E < 1.5 \mu s$   
(LTE TDD, TD-SCDMA)

**PRTC:** Primary Reference Time Clock  
**T-GM:** Telecom Grandmaster  
**T-TSC:** Telecom Time Slave Clock

Note: to be moved into G.8271.1



# NOISE SOURCES



# NOISE ACCUMULATION



- › Total Error  $TE_{TOT}$  is the sum of a constant time error component and a dynamic time error component
  - it is assumed that frequency offset and drift components are not present

$$\left( \sqrt{M} \right) \cdot TE_{DYNPP} \leq TE_{TOT} \leq \left( \left( \sqrt{M} \right) \cdot TE_{DYNPP} + M \cdot TE_{CONST} + \Delta_{LINKASYM} \right)$$

$TE_{CONST}$  = absolute value of the constant time error introduced in any clock in the chain

$TE_{DYNPP}$  = peak-to-peak range of the random time error component introduced in any clock in the chain;

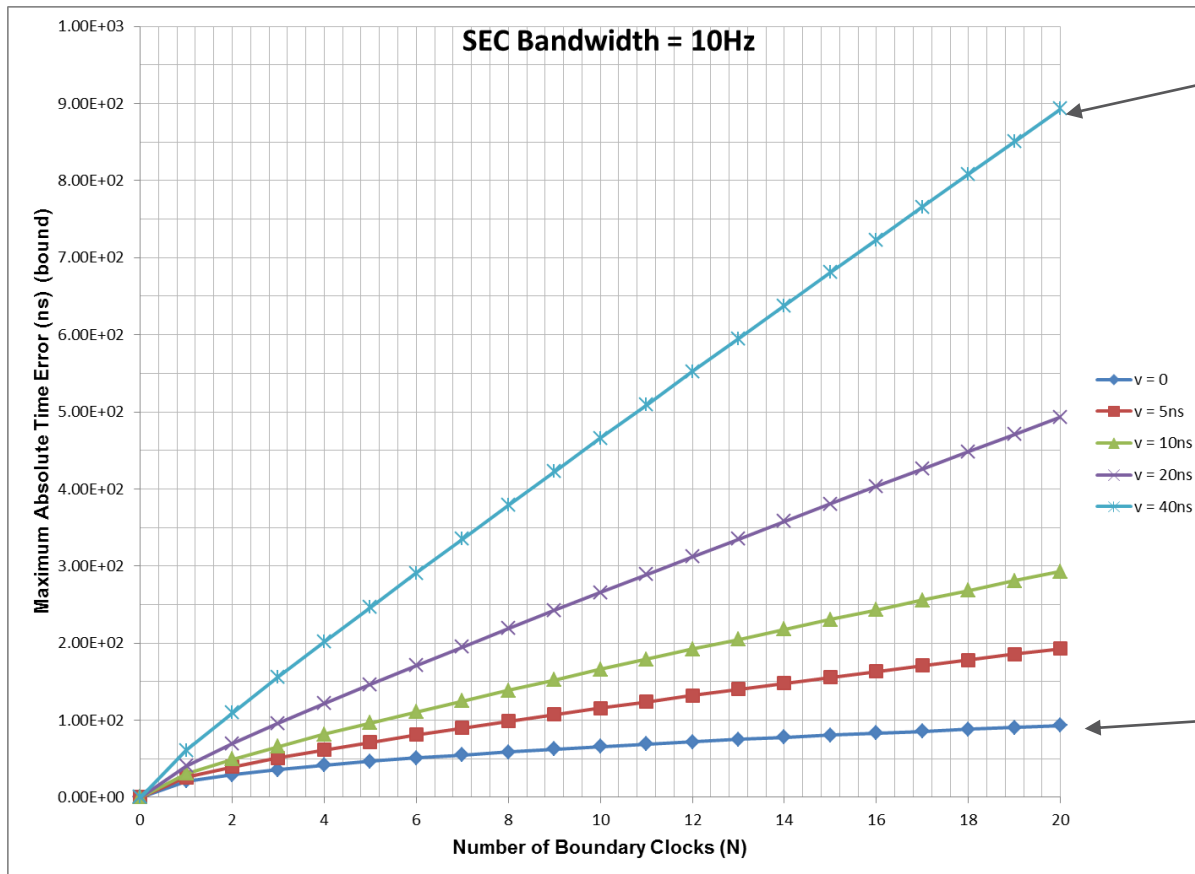
$\Delta_{LINKASYM}$  = total link asymmetry component resulting from the interconnection between the clocks in the chain

# EXAMPLE OF TIME ERROR ACCUMULATION



Accumulation of maximum absolute time error over a chain of boundary clocks for different values of asymmetry bias.

The physical layer assist involves SEC/EEC chain with bandwidth 10Hz.



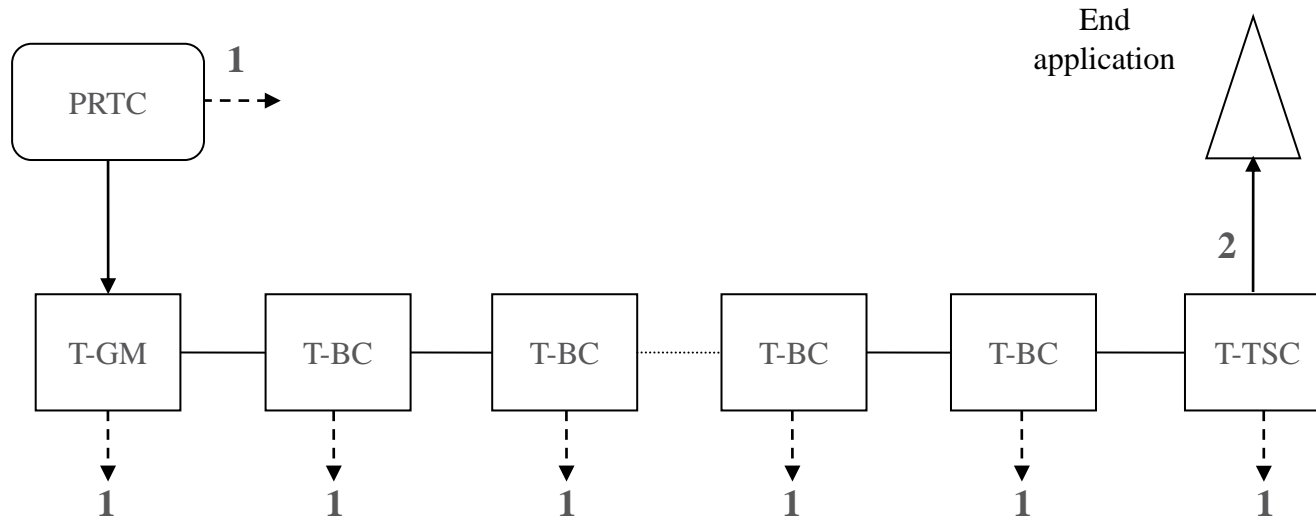
40 ns asymmetry per hop

Source: WD25 (Anue),  
York, September 2011

no asymmetry

$v = \text{max asymmetry per hop}$

# TIME INTERFACES



From G.8271

Reference point 1: measurement interfaces

Reference point 2: distribution interface

Specified in G.8271:

- 1PPS V.11 interface
- 1PPS 50Ω phase synchronization measurement interface

Physical and connector details planned to be included in G.703

# G.8271.1: NETWORK LIMITS



## › Scope

- maximum network limits of phase and time error that shall not be exceeded.
- minimum equipment tolerance to phase and time error that shall be provided at the boundary of these packet networks at phase and time synchronization interfaces.
- Related Information (HRM, Simulation assumptions, etc.)

## › Draft Available (WD8271.1ND)

- Planned for consent in July 2013

## › Details on Simulations in G.Supp

- Planned for 2013

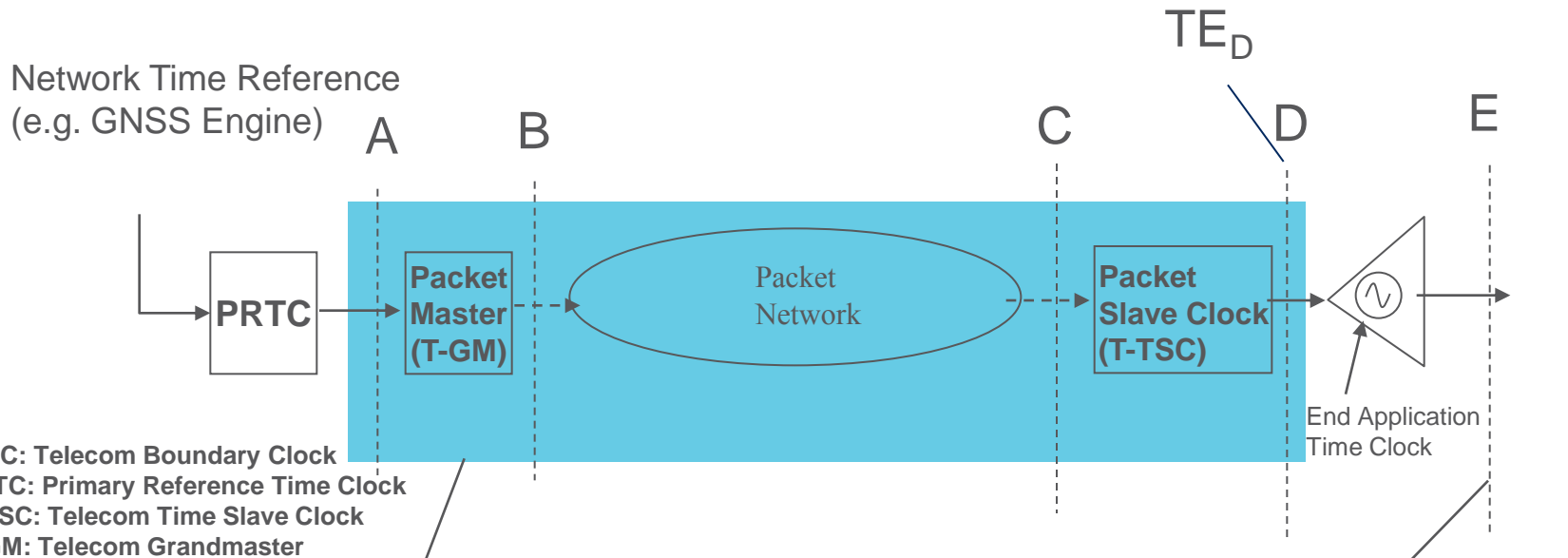
# NOISE (TIME ERROR) BUDGETING ANALYSIS



Focus on Max absolute Time Error

Common Time Reference (e.g. GPS time)

N



Simulation Reference Model:

Typical Target Requirements  $TE_E < 1.5 \mu s$   
(LTE TDD, TD-SCDMA)

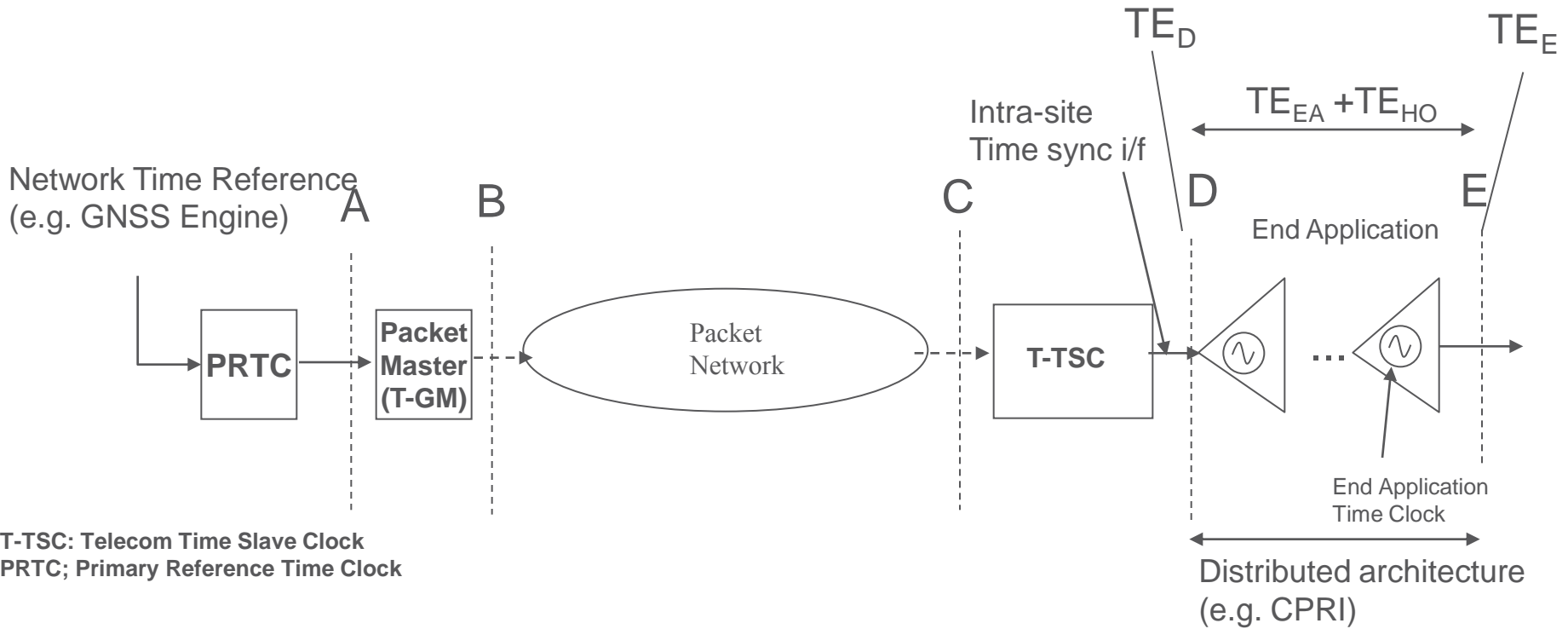
- chain of T-GM, 20 (or 10) T-BCs, T-TSC
- with and without SyncE support

*Limits in "D" ( $TE_D$ ) applicable only in case of External Packet Slave Clock*

# DEPLOYMENT CASE 2: EXTERNAL T-TSC

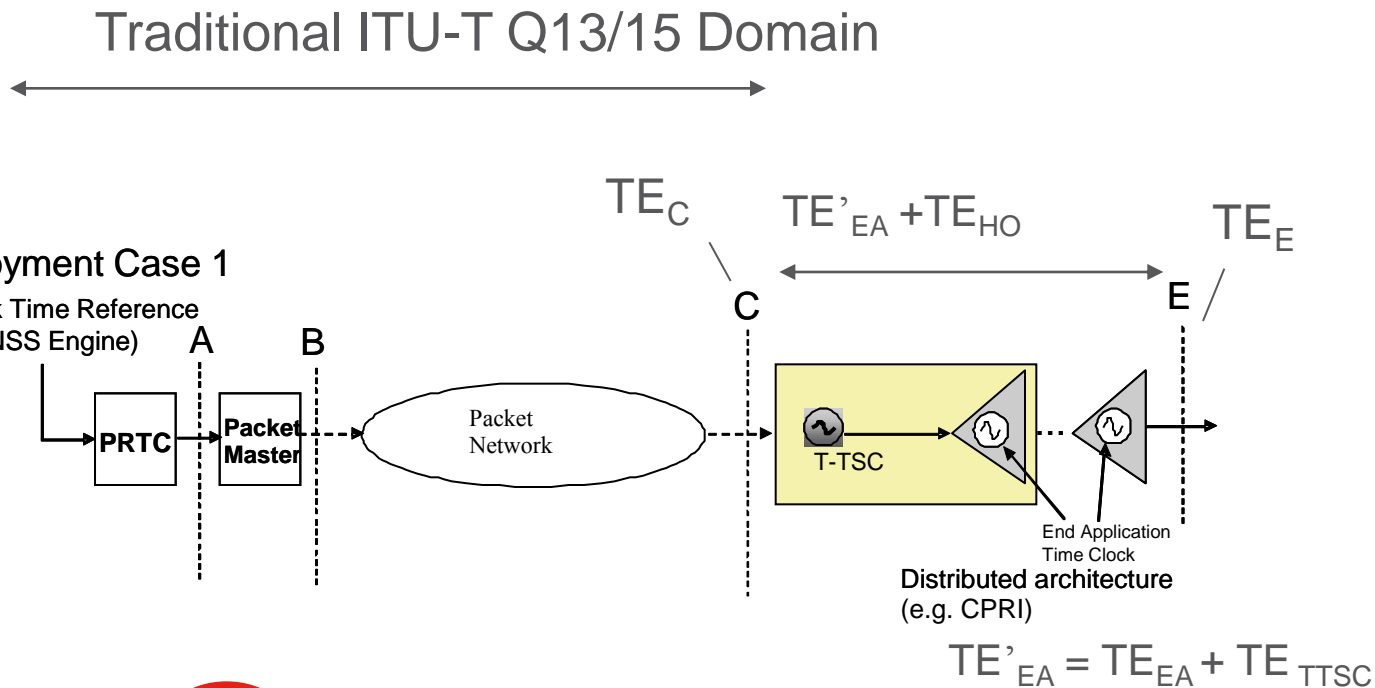


Traditional ITU-T Q13/15 Domain



$$\text{Max } |TE_E| = TE_D + TE_{EA} + TE_{HO} \text{ (Holdover, Rearrangements)}$$

# DEPLOYMENT CASE 1: T-TSC INTEGRATED IN THE END APPLICATION



$$\text{Max } |TE_E| = TE_C + TE'_E + TE_{HO} \text{ (Holdover, Rearrangements)}$$

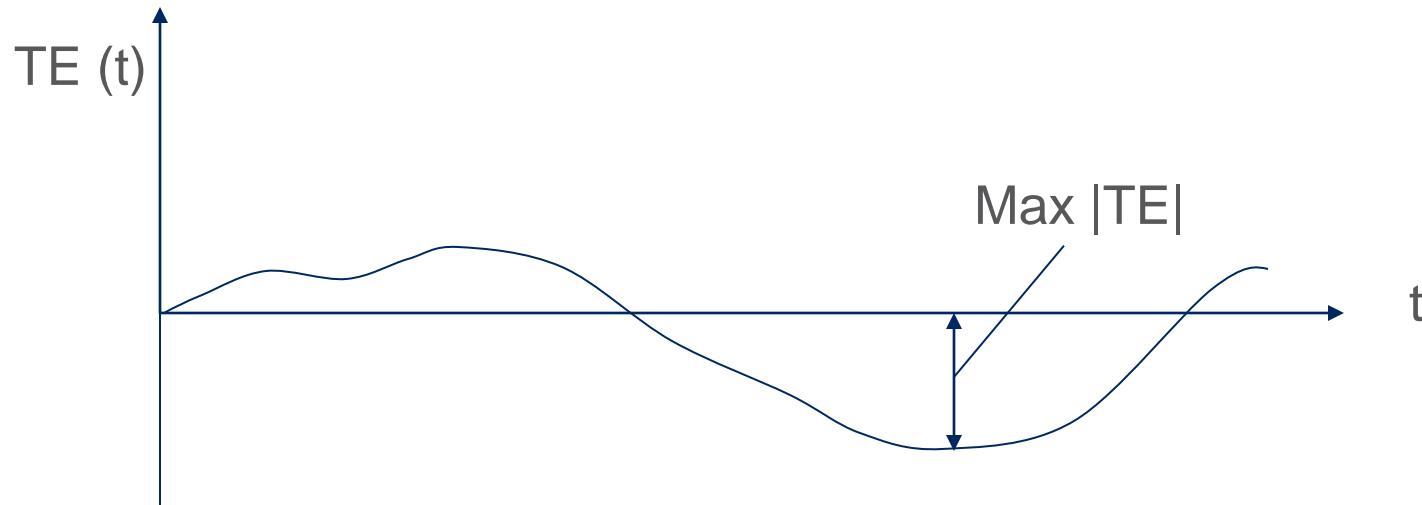
*Ongoing discussions on how to define the network limits in this case*



# METRICS FOR NETWORK LIMITS?



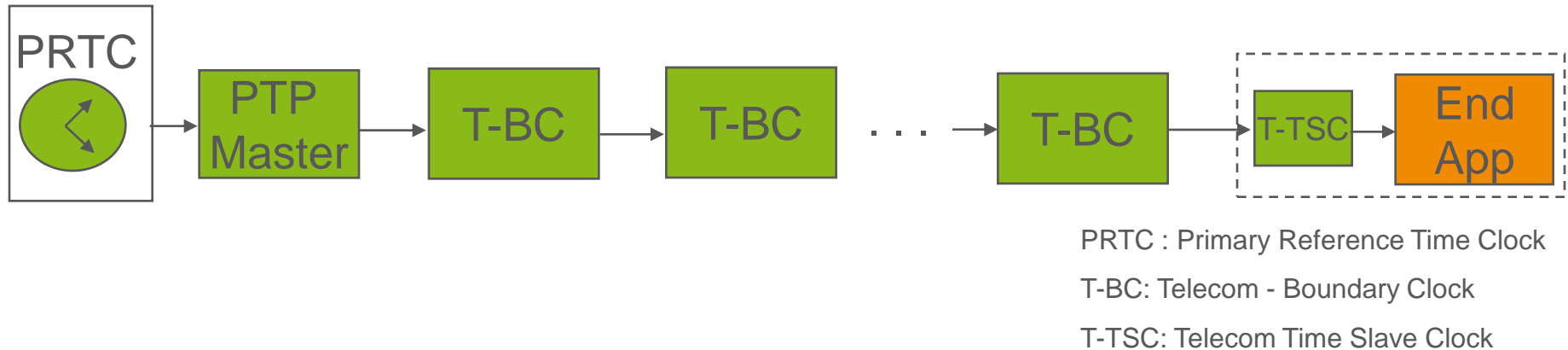
- › Main Focus is Max Absolute Time Error (Max  $|TE|$ )
  - Measurement details (measurement duration, tolerance in the measurement, e.g. 6 sigma) need further discussion



- › Stability aspects also important
  - MTIE? TDEV?
  - Related to End Application filtering capability (Max  $|TE|$  is derived from requirements applicable to the radio interface)
  - Different considerations depending where measurement is made (ongoing discussion especially for Deployment case 1)

# SIMULATIONS: REFERENCE CHAIN WITH BC IN EVERY NODE

- › Removal of PDV and asymmetry in the nodes by means of IEEE1588 support (e.g. Boundary Clock in every node).

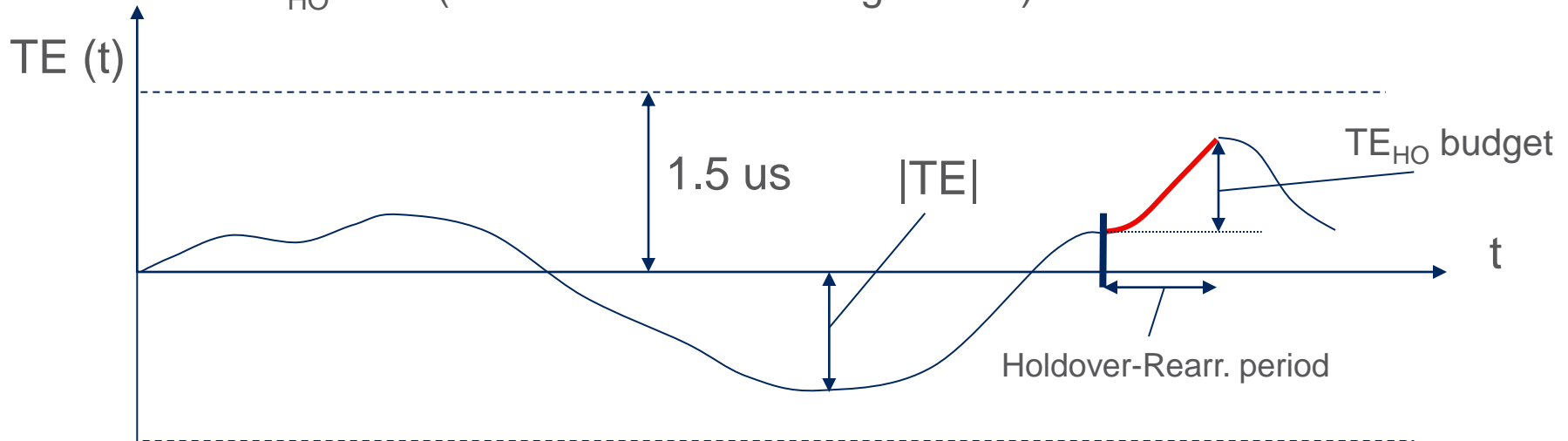


- › Ideally the full support can provide very accurate timing, however several sources of errors still remains:
  - › Simulations are developed to analyse the “Random Component” during normal conditions and during rearrangements; with and without SyncE
  - › Considerations on the “Static Component” are made separately
- › Simulations with partial timing support will require the definition of new HRMs (in G.8271.1 or 8271.2?)

# REARRANGEMENTS AND HOLDOVER



- › The full analysis of time error budgeting includes also allocating a suitable budget to the  $TE_{HO}$  term (Holdover and Rearrangements)



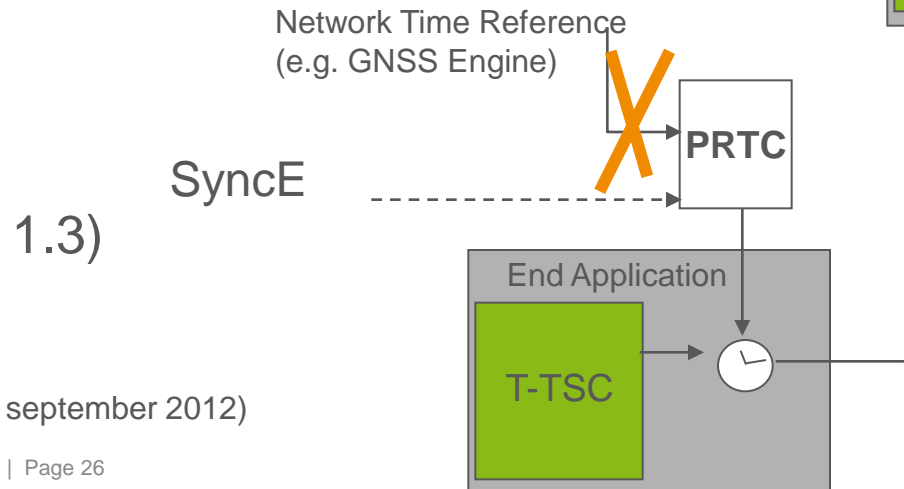
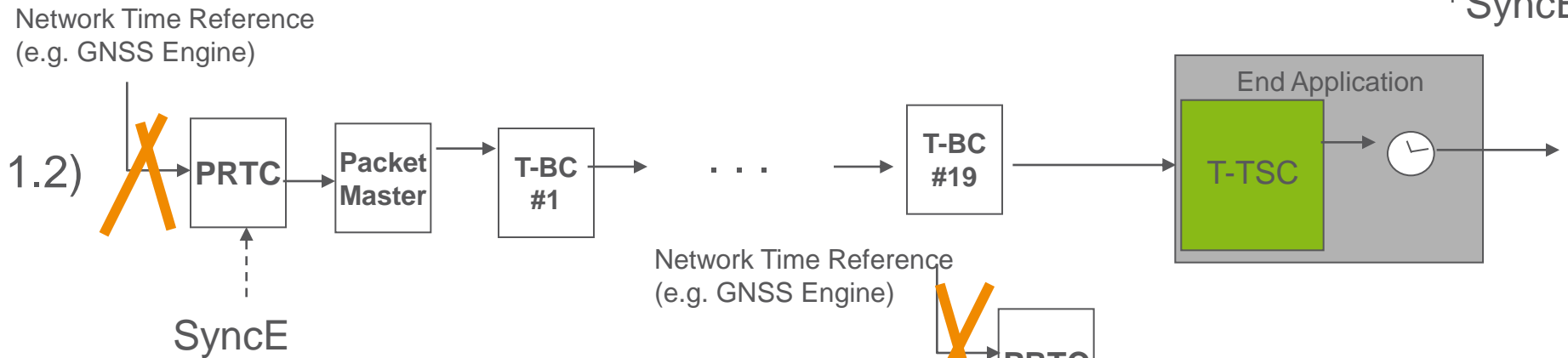
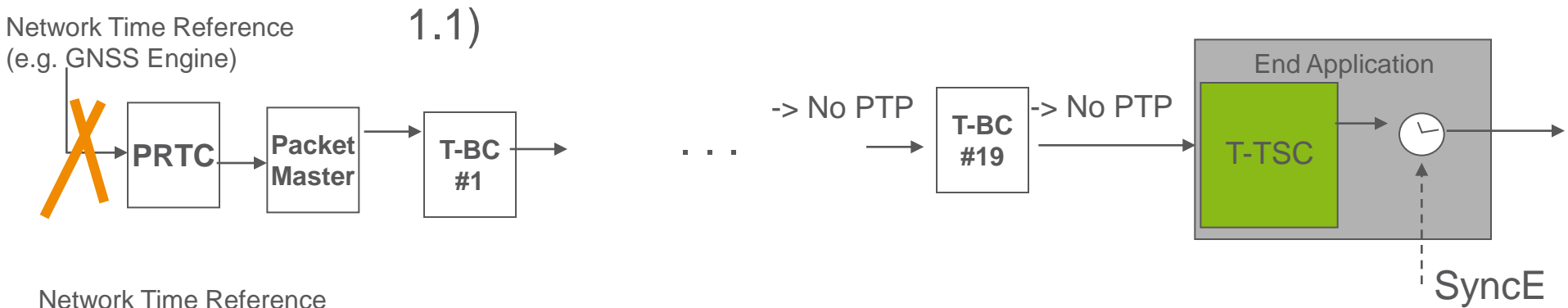
- › Holdover

- **Scenario 1:** PTP traceability is lost and the End Application or the PRTC enters **holdover** using SyncE or a local oscillator

- › Rearrangements

- **Scenario 2:** PTP traceability to the primary master is lost; the End Application **switches** to a backup PTP reference **with** physical layer frequency synchronization support
- **Scenario 3:** PTP traceability to the primary master is lost; the End Application **switches** to a backup PTP reference **without** physical layer frequency synchronization support

# ANALYSIS OF TIME HOLDOVER (SCENARIO 1)



Source WD07 (Q13/15, Geneva september 2012)

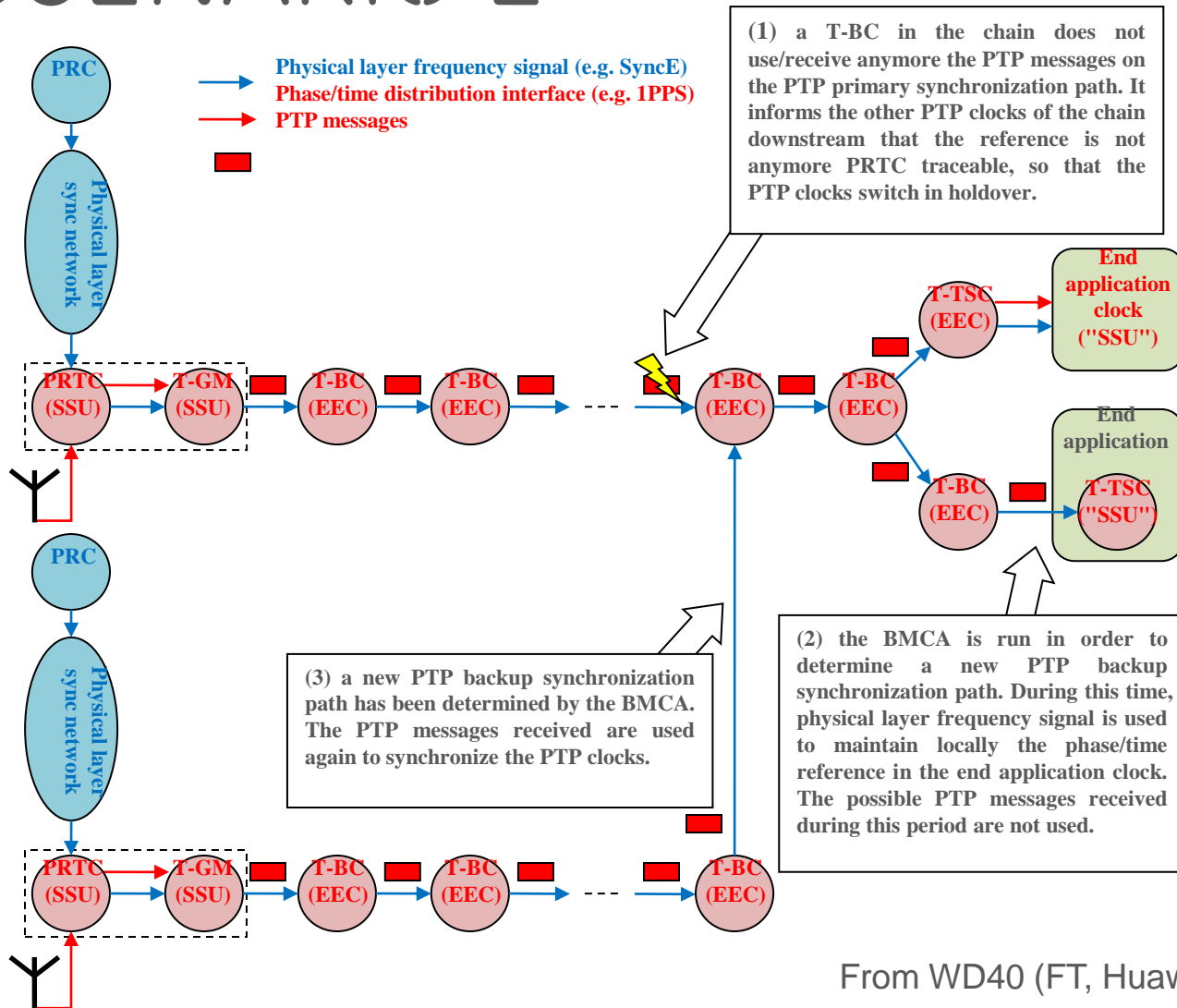
# TIME HOLDOVER SCENARIOS



| Protection Scenario | Short Holdover period<br>e.g. 5 min max<br>(e.g. for short Interruptions)                   | Long Holdover period<br>e.g. 3-8 hours<br>(e.g. for Long Interruptions)                          | Very long Holdover period<br>e.g. 1-3 days<br>(e.g. for Very Long Interruption)  | Available Budget<br>(for 1.5 $\mu$ s use case)                | Considerations  |
|---------------------|---|--|--|---|---|
| 1.1                 | OK according to simulations, both G.812 Type III in holdover or use of SyncE are applicable | <b>NOK</b> according to current simulations  | <b>NOK</b> according to current simulations  | TBD<br>(e.g. values in the order of 400ns have been proposed) | Very long period holdover looks challenging at the moment with current assumptions. |
| 1.2                 | OK according to simulations, both G.812 Type III in holdover or use of SyncE are applicable | <b>NOK</b> according to current simulations  | <b>NOK</b> according to current simulations  | TBD<br>(e.g. values in the order of 400ns have been proposed) | Very long period holdover looks challenging at the moment with current assumptions. |
| 1.3                 | OK according to simulations, both G.812 Type III in holdover or use of SyncE are applicable | OK according to simulations, but only with the use of SyncE, not with G.812 Type III in holdover | Should be OK according to simulations (to be confirmed), but only with the use of SyncE, not with G.812 Type III in holdover | TBD<br>(e.g. 1.25 $\mu$ s*)                                   | In general this use case looks ok for all holdover periods when SyncE is used       |

\*1.25 = 1.5 – 0.25 ; where 0.25  $\mu$ s = PRTC accuracy (100ns) + budget of base station (150ns)

# REARRANGEMENTS: SCENARIO 2

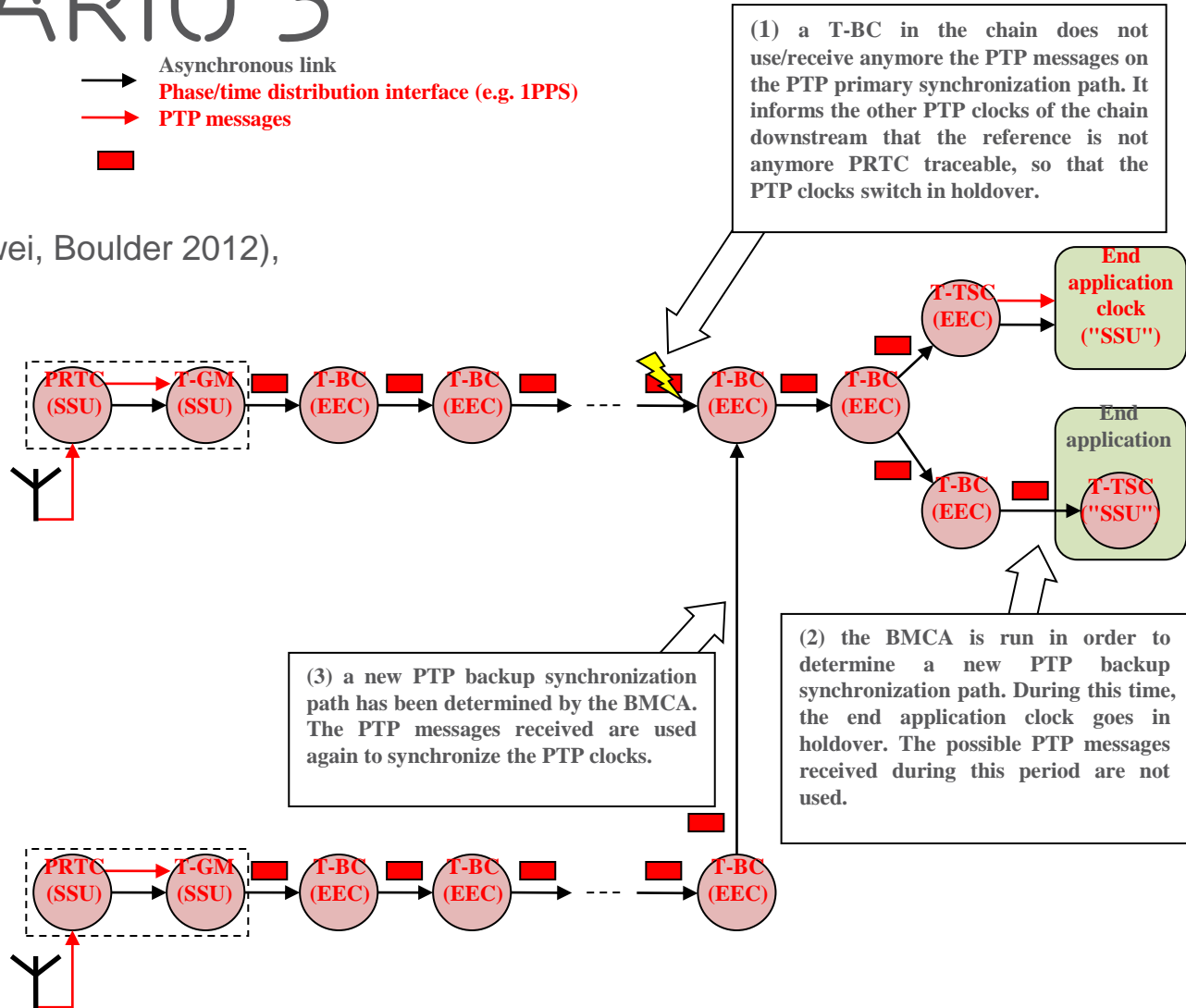


From WD40 (FT, Huawei, Boulder 2012)

# REARRANGEMENTS: SCENARIO 3



From WD40 (FT, Huawei, Boulder 2012),



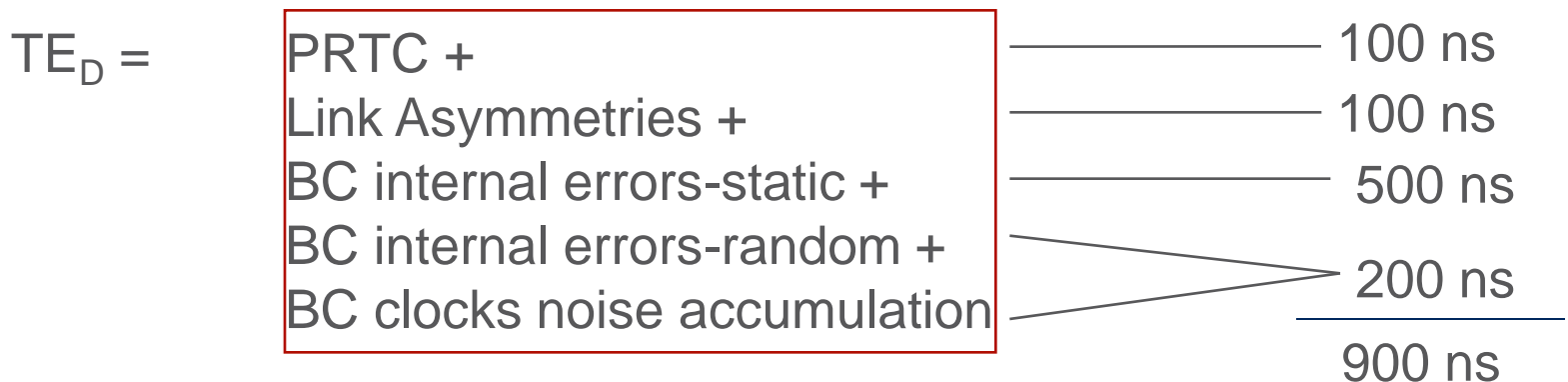
Rearrangements could be controlled within **150 ns** assuming the Time clock allows for fast start up  
 If this is not possible a higher budget would be required instead (about **400 ns**).

# SIMULATIONS RESULTS AND TIME ERROR BUDGETING



- › Several simulations have been performed using HRM with SyncE support
- › The most challenging scenarios are related to ring rearrangements in SyncE network.
- › It seems feasible to control the max |TE| in the 150/200 ns range
  - in the worst case a few mHz filtering would be required
- › It is assumed that the nodes in a PTP chain without syncE should be designed in order to accumulate similar level of noise

## Budgeting Example for Deployment case 2



600 ns available for Holdover, Intra-site time sync and End Application



# SUMMARY



- › G.8271 and G.8271.1 provide the fundamentals for Time synchronization: methods, network requirements
  - G.8271 recently released; G.8271.1 and G.8271 Amendment planned in 2013.
- › Some important aspects need to be clarified:
  - T-TSC embedded in a Base Station (where are the limits defined/measured)
  - Filtering of SyncE noise
  - Stability requirements
- › The budget for the Time sync Holdover is a key parameter in the noise budgeting analysis
- › Allocation of Static noise between links and network equipments
- › Analysis of Partial Timing Support require the definition of new simulation models and new HRMs (in 8271.2?)



**ERICSSON**